Score Distillation via Reparametrized DDIM

Ours (SDI)

We provide a theoretical

analysis and suggest a fix



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TL;DR

Score Distillation Sampling (SDS) [1] is a promising technique that allows to use pre-trained 2D diffusion models for 3D generation. However, the quality of the generated 3D assets is limited. In this work we:

Theoretically show that SDS ≈ 2D Diffusion

Reveal that the noise term in SDS is the reason for over-smoothing

X Suggest a fix

Improve the quality of 3D generation

2D Diffusion (DDIM)



Image Diffusion generates crisp, high-quality images

model.





Score Distillation Sampling uses Image Diffusion, but the results are blurry

Proposed in DreamFusion [1] and Score Jacobian Chaining [2], Score Distillation is

a method for generating 3D shapes using a pre-trained and frozen 2D diffusion

5. Optimize the parameters of the 3D representation to match the denoised

Often the generated shapes are over-smoothed and over-saturated.

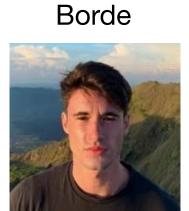
How does Score Distillation work?

SDS is a dual process of DDIM

A single upate step of Denoising Diffusion Implicit Models (DDIM) [3] sampling algorithm removes a portioin of the predicted noise to match the noise level of the next step:

















$\bar{x}(t-\tau) = \bar{x}(t) + \epsilon_{\theta}^t \left(\sqrt{\alpha(t)} \bar{x}(t), y \right) \left[\sigma(t-\tau) - \sigma(t) \right].$

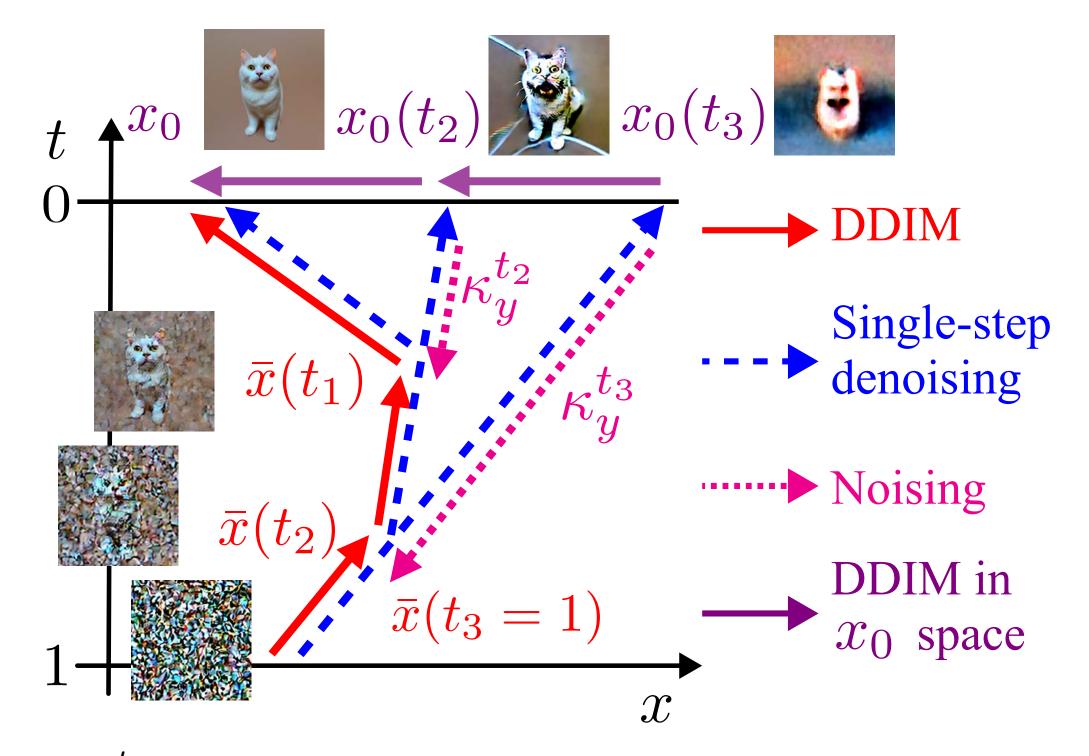
Let's consider a new variable that is formed by denoising the images in a single step:

$$x_0(t) \triangleq \bar{x}(t) - \sigma(t)\epsilon_{\theta}^t(x(t), y).$$

With a simple change of variable in the DDIM update rule, we obtain a dual process of DDIM defined for the space of noise-free images:

$$x_0 \text{ noised with } \kappa_y^t \text{ to time } t - \tau$$

$$x_0(t - \tau) = x_0(t) - \sigma(t - \tau) \left[\underbrace{\epsilon_\theta^{t - \tau} \left(\sqrt{\alpha(t - \tau)} x_0(t) + \sqrt{1 - \alpha(t - \tau)} \kappa_y^t \left(x_0(t) \right), y \right) - \underbrace{\kappa_y^t \left(x_0(t) \right)}_{\text{noise sample } \kappa_y^t} \right]}_{\text{predicted noise}}$$



,where κ_{u}^{v} is a noise term added to the current image. For the new process to match DDIM exactly, it should satisfy the following stationary-point equation:

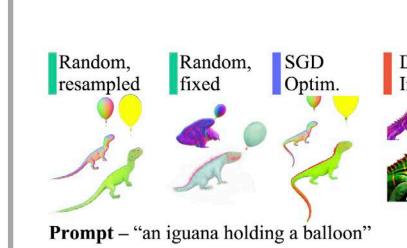
$$\kappa_y^t = \epsilon_\theta^t \left(\sqrt{\alpha(t)} x_0(t) + \sqrt{1 - \alpha(t)} \kappa_y^t, y \right)$$

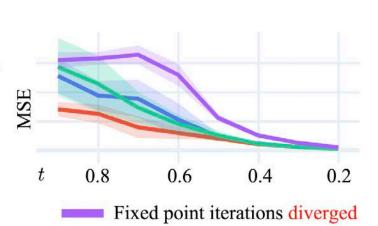
Solving this equation precisely is very hard as it involves inverting a higly non-linear and high-dimentional Neural Network. A naive solution that we can adopt is to sample the noise term randomly from the Normal Gaussian distribution.

$$\kappa_y^t \sim \mathcal{N}(0, I)$$

In this case the re-parametrization of DDIM precisely matches SDS update rule!

Random noise is the reason of blurriness



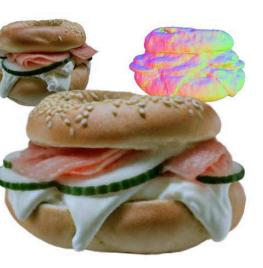


Due to the randomness in choise of κ_{u}^{ν} SDS's optimization process is being averaged acrross multiple trajectories of DDIM, what causes bluriness. In this work we explore multiple approaches to solving the stationary point equation and find that running DDIM in the inverse direction yields the most accurate solution. In this case Score Distillation optimisation process becomes time- and spatial-consistent.

3D generation quality gets closer to 2D models



"photograph of a black leather backpack"



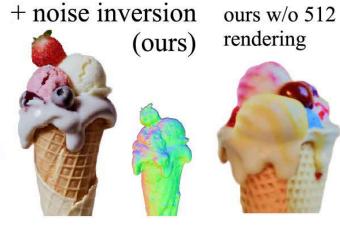
"bagel filled with cream cheese and lox"



"a DSLR photo of Cthulhu"

+ 512 rendering + t annealing







See the paper for detailed comparisons with ProlificDreamer, Noise-Free SD, HiFA, Lucid Dreamer, and other amazing works in Score Distillation

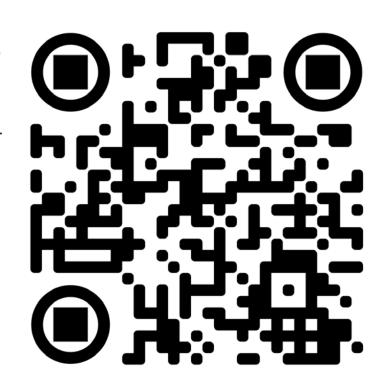
References

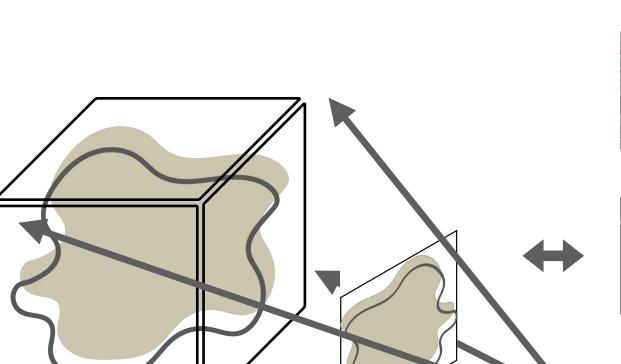
[1] Poole, Ben, et al. "DreamFusion: Text-to-3D using 2D Diffusion." The Eleventh International Conference on Learning Representations.

[2] Wang, Haochen, et al. "Score jacobian chaining: Lifting pretrained 2d diffusion models for 3d generation." Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition. 2023.

[3] Song, Jiaming, Chenlin Meng, and Stefano Ermon. "Denoising diffusion implicit models." arXiv preprint arXiv:2010.02502 (2020).

MORE ABOUT THE WORK lukoianov.com/sdi





I. Initialize a differentiable 3D representation

4. Denoise the image with the 2D diffusion model

1. Sample a random camera pose

II. Repeat steps 1-5 until convergence

2. Render a view of the object 🧧

3. Add noise to the rendering

image 🎯

NeRF

